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GENERALISATION OF OPACITY FORMULAS FOR NEUTRON TRANSPORT



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INTRODUCTION

In the context of reactor physics, one is often called to relate the physical properties of a medium to the statistics of the random trajectories of the neutrons flowing through it. To this aim, we focus on the Cauchy's formula, which establishes a link between the average length of the neutron paths (proportional to the medium opacity) and the volume-to-surface ratio of the traversed medium. Originally established for random straight lines, this formula was recently shown to apply also to Pearson random flights [1–3], and to branching exponential flights [4,5]. In this work, thanks to a Feynman-Kac approach [4], we consider some extensions of such results for neutrons undergoing scattering, absorption and branching, in heterogeneous and anisotropic media. A validation of the proposed formulas via Monte Carlo simulations is discussed. The simplicity of some of these opacity formulas might provide a useful tool for the validation of a Monte Carlo code.

MEDIUM AND HYPOTHESIS

Properties of the medium :

• heterogeneous,



BRANCHING EXPONENTIAL FLIGHTS

The paths performed by neutrons are random in nature, and can be modelled by resorting to a stochastic process: the branching exponential flights.



 $C(\omega \to \omega')$ • anisotropic: scattering kernel $C_{scat}(\vec{\omega} \to \vec{\omega}')$; isotropic fission kernel $C(\vec{\omega} \to \vec{\omega}') = cst$.

Hypotheses:

- the velocity v of the neutron is assumed constant along the trajectory;
- media have vacuum boundary conditions.

INTERESTING QUANTITIES

The **opacity** Ω is proportional to the average length travelled in the volume V by the particles that are injected uniformly at its surface $S : \langle L \rangle_S$.



Two other observables are also relevant,

• total **number of** occured **collisions** in V,



At each time step dt, the neutron :

- collides with a nucleus of the medium, with a probability $\sigma v dt$
- has no interaction with the medium and goes straight ahead, with a probability $(1 - \sigma v dt)$

When neutrons interact with the medium, they

- are scattered on a nucleus with a probability p_{scat} and a kernel C_{scat}
- are captured by a nucleus with p_{capt} and then $k_{k\geq 0}$ neutrons are emitted by the nucleus with a probability p_k in a direction given by C.

BACKWARD EQUATION FOR THE *m***-TH MOMENT OF THE TRACE** L^m

We followed the lines of the Feynman-Kac formalism and found the backward equation for $L^m(\vec{r_0}, \vec{\omega_0}, t)$:

$$\frac{1}{v}\frac{\partial L^{m}}{\partial t} = \mathcal{L}^{*}L^{m} + \underbrace{mV(\vec{r_{0}},\vec{\omega_{0}})L^{m-1}}_{past\ history} + \underbrace{\sigma(\vec{r_{0}})p_{cap}(\vec{r_{0}})\sum_{j=2}^{m}\nu_{j}(\vec{r_{0}})B_{m,j}[C^{*}\{L^{i}\}]}_{purely\ branching\ term},$$
where
$$\mathcal{L}^{*} = \underbrace{\vec{\omega_{0}}.\vec{\nabla}_{\vec{r_{0}}} - \sigma(\vec{r_{0}})}_{streaming} + \underbrace{\sigma(\vec{r_{0}})p_{cap}(\vec{r_{0}})\nu_{1}(\vec{r_{0}})C^{*}\{.\}}_{emission\ after\ capture}} + \underbrace{\sigma(\vec{r_{0}})p_{scat}(\vec{r_{0}})C^{*}_{scat}\{.\}}_{scattering}.$$

$$B_{m,j}[z_{i}] = B_{m,j}[z_{1},\cdots,z_{m-j+1}] \text{ are the Bell's polynomials.}$$

• the survival probability S_t , which is the probability that at time *t* at least one particle is still in *V*.

 $\nu_i(\vec{r_0}) = \langle k(k-1)\cdots(k-j+1) \rangle$ are the falling factorial moments.

 $\nu_1(\vec{r_0}) = \sum_k k p_k(\vec{r_0})$ is the average number of descendants per generation.

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STATIONARY MOMENTS AND AVERAGES: TRAVELLED LENGTH $\langle L^m angle$

If the particle losses due to absorptions in V and leakages from the boudaries are larger than the gain due to population growth, then the limit $\lim_{t \to +\infty} L^m(\vec{r_0}, \vec{\omega_0}, t)$ exists. In this case, we obtain the equation for the stationary moments of the travelled lenght L^m . By integrating this equation uniformly over all initial positions and directions in the volume V, we get:

$$\underbrace{\left\langle L^{m}\right\rangle_{S}}_{entering \ flux} = \eta_{d} \frac{V}{S} \left[\underbrace{m \left\langle L^{m-1}\right\rangle_{V}}_{past \ history} - \underbrace{\left\langle \sigma(\vec{r_{0}})L^{m}\right\rangle_{V}}_{loss \ by \ collisions} + \underbrace{\left\langle \sigma(\vec{r_{0}}) \ p_{scat}(\vec{r_{0}}) \ C^{*}_{scat}\{L^{m}\}\right\rangle_{V}}_{scattering} + \underbrace{\left\langle \sigma(\vec{r_{0}}) \ p_{cap}(\vec{r_{0}}) \nu_{1}(\vec{r_{0}})L^{m}\right\rangle_{V}}_{emission \ after \ capture} + \underbrace{\sum_{j=2}^{m} \left\langle \sigma(\vec{r_{0}}) \ p_{scat}(\vec{r_{0}}) \ \nu_{j}(\vec{r_{0}}) \ B_{m,j}[C^{*}\{L^{i}\}]\right\rangle_{V}}_{purely \ branching \ term} \right].$$

Average length $\langle L \rangle$ - General Case

$$\langle L \rangle_S = \eta_d \frac{V}{S} \left(1 + \left\langle \sigma(\vec{r_0}) \left(\mathcal{V} - 1 \right) L \right\rangle_N \right), \quad \text{where } \mathcal{V} = p_{cap}(\vec{r_0}) \, \nu_1(\vec{r_0}) + p_{scat}(\vec{r_0}) \, C^*_{scat}\{.\} \, .$$



CRITICAL CASE, $\nu_1 = 1$

In this case, the formula (3) can be simplified. Then we recover the Cauchy formula's:

$$\left\langle L \right\rangle_S = \eta_d \frac{V}{S} \; .$$

• Homogeneous medium (black): $\sigma = 1$ • Heterogeneous medium (red): $\sigma_{1|2} = 1|0.5|$ • Anisotropic medium (blue): $\sigma = 1$

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