### Poisson formula on the disk [7]

- 1. a) [1]  $f(z_0) = \frac{1}{2\pi i} \oint_{\mathcal{C}} \frac{f(z)}{z z_0} dz.$ 
  - b) [2] Clearly, the point  $1/\bar{z}_0$  lies outside the circle C so there is no pole inside the circle. We get  $0 = \frac{1}{2\pi i} \oint_{\mathcal{C}} \frac{f(z)}{z 1/\bar{z}_0} dz.$
  - c) [2] We subtract the two previous relation in order to rewrite the integrals with real numbers and an angular variable only. We take the parametrization  $z_0 = re^{i\theta}$  and  $z = e^{i\phi}$ ,  $dz = izd\phi$ : first, after calculation

$$\left(\frac{1}{z-z_0} - \frac{1}{z-1/\bar{z}_0}\right)iz = i\frac{1-r^2}{1-2r\cos(\theta-\phi) + r^2}$$

that is inserted into the integral to give the desired result

$$f(z = re^{i\theta}) = \frac{1}{2\pi} \int_0^{2\pi} \frac{1 - r^2}{1 - 2r\cos(\theta - \phi) + r^2} f(e^{i\phi}) \,\mathrm{d}\phi \,. \tag{1}$$

2. [2] Without charges, the electrostatic potential is an harmonic function. So are the real an imaginary parts of the previous f function since it is analytical. With  $f(r,\theta) = f_R(r,\theta) + if_I(r,\theta)$ , we thus have two properties :  $\hat{\Delta}f_R = 0$  and  $\hat{\Delta}f_I = 0$  and both  $f_{R,I}$  satisfy to (1) by taking the real and imaginary part of the Poisson relation. Last, choosing say the real part such that  $f_R(1,\theta) = v(\theta)$ , we have that  $V = f_R$  is solution of the Poisson equation and the value of the potential inside the disk is obtained from

$$V(r,\theta) = \frac{1}{2\pi} \int_0^{2\pi} \frac{1-r^2}{1-2r\cos(\theta-\phi)+r^2} v(\phi) \,\mathrm{d}\phi \;. \tag{2}$$

involving only real numbers.

### Saddle point technique with many variables [8]

We consider the function f(x) of the variable x > 0 defined under the integral form

$$f(x) = \int d\vec{t} \exp\left(-x h(\vec{t})\right)$$
(3)

assuming a entire multivariate real function  $h(\vec{t})$  of d variables that has a single absolute minimum  $\vec{t}_c$ . We assume for sake of simplicity that h is entire and that the integral range if the whole space  $\mathbb{R}^d$  and we take the limit  $x \to \infty$ .

1. [3] We expand h around its minimum  $\vec{t_c}$  to second order

$$h(\vec{t}) \simeq h(\vec{t}_c) + \frac{1}{2} \sum_{i,j=1}^{d} \mathbf{H}_{ij}^c(t_i - t_{c,i})(t_j - t_{c,j})$$

using the notations  $\mathbf{H}_{ij}^c = \frac{\partial^2 h}{\partial t_i \partial t_j} \Big|_{\vec{t}_c}$  for the Hessian matrix that is a positively defined matrix for an absolute minimum (we assume no zero eigenvalue for non-degenerate minimum). The saddle point equation giving the extrema is

$$\vec{\nabla}_{\vec{t}} \, h|_{\vec{t}_c} = \vec{0} \tag{4}$$

Then, the saddle point technique gives

$$f(x) \simeq \exp\left(-xh(\vec{t}_c)\right) \int \mathrm{d}\vec{t} \exp\left(-\frac{x}{2} \sum_{i,j=1}^d \mathbf{H}_{ij}^c(t_i - t_{c,i})(t_j - t_{c,j})\right)$$
(5)

which is a Gaussian integral. We get

$$f(x) \simeq \sqrt{\frac{(2\pi)^d}{\det \mathbf{H}^c}} \frac{e^{-x h(\vec{t}_c)}}{x^{d/2}}$$
(6)

2. [2] The saddle point equation is now

$$\vec{\nabla}_{\vec{t}} \, h|_{\vec{t}_{e}} = \vec{b} \tag{7}$$

so  $\vec{t_c}(\vec{b})$ . Applying the previous result using the fact that the external field  $\vec{b}$  does not change the Hessian matrix, we get

$$Z(x,\vec{b}) \simeq \sqrt{\frac{(2\pi)^d}{\det \mathbf{H}^c(\vec{b})}} \frac{e^{-x \left[h(\vec{t}_c(\vec{b})) - \vec{b} \cdot \vec{t}_c(\vec{b})\right]}}{x^{d/2}}$$
(8)

3. [3] As usual,

$$\left\langle \vec{t} \right\rangle = \frac{1}{Z(x,\vec{0})} \int d\vec{t} \, \vec{t} \, \exp\left[-x \, h(\vec{t})\right] \tag{9}$$

$$= \frac{1}{x Z(x, \vec{0})} \vec{\nabla}_{\vec{b}} \int d\vec{t} \exp\left(-x \left[h(\vec{t}) - \vec{b} \cdot \vec{t}\right]\right) \Big|_{\vec{b}=\vec{0}}$$
(10)

$$= \frac{1}{x} \vec{\nabla}_{\vec{b}} \ln Z(x, \vec{b}) \Big|_{\vec{b} = \vec{0}}$$
(11)

Using the saddle point approximation, we get

$$\frac{1}{x}\ln Z(x,\vec{b}) \simeq -h(\vec{t}_c(\vec{b})) + \vec{b} \cdot \vec{t}_c(\vec{b}) - \frac{d}{2x}\ln(x/2\pi) - \frac{1}{2x}\ln\det\mathbf{H}^c(\vec{b})$$

The last two terms can be neglected when  $x \to \infty$ . The first two give

$$\left< \vec{t} \right> \simeq - \vec{\nabla}_{\vec{b}} h(\vec{t}_c(\vec{b}\,)) + \vec{t}_c(\vec{b}\,) + \vec{b} \cdot \vec{\nabla}_{\vec{b}} \vec{t}_c(\vec{b}\,)$$

but by chain rule, we have  $\vec{\nabla}_{\vec{b}}h = \vec{\nabla}_{\vec{t}}h \cdot \vec{\nabla}_{\vec{b}}\vec{t}_c(\vec{b}) = \vec{b} \cdot \vec{\nabla}_{\vec{b}}\vec{t}_c(\vec{b})$  where we have used the saddle point equation in the last equality so that finally:

$$\langle \vec{t} \rangle \simeq \vec{t}_c(\vec{b})$$

## Green's function for 1D and 2D waves [12]

1. [1] t' and  $\vec{r}'$  are the time and position of the impulse. In free space with translational and rotational invariance, we expect the Green's function to depend only on the relative distance  $\vec{R} = \vec{r} - \vec{r}'$  (actually its norm) and the time from impulse  $\tau = t - t'$ .

We'll note  $R = \|\vec{R}\|$ .

2. [2] Fourier transforming the equation after changing variables to

$$\left[\hat{\Delta}_{\vec{R}} - \frac{\partial^2}{\partial \tau^2}\right] G(\vec{R}, \tau) = \delta(\vec{R})\delta(\tau) \quad \text{gives} \quad (\omega^2 - \vec{k}^2)\tilde{G}(\vec{k}, \omega) = 1$$
(12)

so, with  $k = \|\vec{k}\|$ ,

$$G(\vec{R},\tau) = \int \frac{\mathrm{d}\vec{k}}{(2\pi)^d} \int \frac{\mathrm{d}\omega}{2\pi} \, \frac{e^{i(\vec{k}\cdot\vec{R}-\omega\tau)}}{\omega^2 - k^2} \tag{13}$$

3. [2] For the integral over  $\omega$ , we have two poles  $\omega = \pm k$  lying on the real axis. We regularize this integral using the causal regularization by shifting these poles below the real axis to  $\omega = \pm k - i\varepsilon$ ,  $\varepsilon \to 0^+$ . Then, for  $\tau < 0$ , we compute the integral using the upper half-circle and residue theorem, which gives zero since there is no poles. For  $\tau > 0$ , we must use the lower half-circle. Adding the contribution of the two poles, we get

$$G(\vec{R},\tau) = -\Theta(\tau) \int \frac{\mathrm{d}\vec{k}}{(2\pi)^d} \,\frac{\sin(k\tau)}{k} \,e^{i\vec{k}\cdot\vec{R}} \tag{14}$$

with  $\Theta$  the Heavyside function, that accounts for vanishing of the integral when  $\tau < 0$ .

4. d = 1 case

a) [1] Using the result of the lecture / tutorial, we know that  $\int_{-\infty}^{\infty} \frac{\sin(u)}{u} du = \pi$ . Now, we the y variable, if we write  $I(y) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{\sin(ky)}{k} dk$ , we have I(y) = 0 if y = 0, using u = ky, I(y) = +1 if y > 0 and I(y) = -1 if y < 0 (it is the sign function !). In the end, we can use

$$I(y) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{\sin(ky)}{k} dk = 2\Theta(y) - 1$$

b) [2] First

$$G(x,\tau) = -\Theta(\tau) \int \frac{\mathrm{d}k_x}{2\pi} \, \frac{\sin(k\tau)}{k} \, \cos(k_x x) = -\Theta(\tau) \int \frac{\mathrm{d}k_x}{2\pi} \, \frac{\sin(k_x \tau)}{k_x} \, \cos(k_x x) \tag{15}$$

Using  $\cos(k_x x)\sin(k_x \tau) = \frac{1}{2}[\sin(k_x(\tau+x)) + \sin(k_x(\tau-x))]$ , we get

$$G(x,\tau) = -\frac{\Theta(\tau)}{4} [I(x+\tau) + I(\tau-x)] = -\frac{\Theta(\tau)}{2} [\Theta(x+\tau) + \Theta(\tau-x) - 1]$$
(16)

With  $\tau > 0$ , the last term can be shown to be equal to  $\Theta(\tau - |x|)$  and then, the condition  $\Theta(\tau)$  can get absorbed since non-zero result requires  $\tau > |x| > 0$ .

$$G(x,\tau) = -\frac{1}{2}\Theta(\tau - |x|)$$
(17)

5. d = 2 case

a) [1] Eq. (14) in polar coordinates  $(k, \theta)$  in k-space reads

$$G(R,\tau) = -\Theta(\tau) \int_0^\infty \int_0^{2\pi} \frac{k \mathrm{d}k \mathrm{d}\theta}{(2\pi)^2} \frac{\sin(k\tau)}{k} e^{ikR\cos\theta} = -\Theta(\tau) \int_0^\infty \frac{\mathrm{d}k}{2\pi} \sin(k\tau) J_0(kR)$$
(18)

with the Bessel function  $J_0(\alpha) = \frac{1}{2\pi} \int_0^{2\pi} \mathrm{d}\theta \; e^{i\alpha\cos\theta}$ 

b) [3] Using the Bessel function identity for real  $\alpha$ 

$$J_0(\alpha) = \frac{2}{\pi} \int_1^\infty \mathrm{d}u \frac{\sin(\alpha \, u)}{\sqrt{u^2 - 1}} \tag{19}$$

we get

$$G(R,\tau) = -\frac{\Theta(\tau)}{2\pi} \int_{1}^{\infty} \frac{\mathrm{d}u}{\sqrt{u^2 - 1}} \underbrace{\frac{2}{\pi} \int_{0}^{\infty} \mathrm{d}k \, \sin(k\tau) \, \sin(kR\,u)}_{\delta(Ru-\tau)} = -\frac{\Theta(\tau)}{2\pi R} \int_{R-\tau}^{\infty} \mathrm{d}\xi \frac{\delta(\xi)}{\sqrt{((\xi+\tau)/R)^2 - 1}} \tag{20}$$

if  $R - \tau < 0, 0$  is not in the range of the integral so the result is zero. It gives an overall  $Theta(\tau - R)$  factor that can be merged with the  $\Theta(\tau)$ . One eventually gets

$$G(R,\tau) = -\frac{\Theta(\tau - R)}{2\pi\sqrt{\tau^2 - R^2}}$$
(21)

which somehow interpolates between the light-cone result in 1D and the pulse result in 3D.

# Laguerre's polynomials [19]

### **General properties**

1. [1] Applying the result (6.5) of the lecture, using p(x) = x and q(x) = 1 - x we get:

$$w(x) = \frac{1}{p(x)} \exp\left\{\int^x \frac{q(x')}{p(x')} dx'\right\} = \frac{1}{x} \exp\left\{-\int^x \frac{1-x'}{x'} dx'\right\} = \frac{1}{x} e^{\ln x - x} = e^{-x}$$
(22)

2. [3] Generating function. We use first Schlaefli representation and then resume the series under the integral. We start from the Cauchy integral formula with  $f(z) = z^n e^{-z}$  that is holomorphic and taking  $z_0 = x$ :

$$\frac{\mathrm{d}^{n}}{\mathrm{d}x^{n}}x^{n}e^{-x} = \frac{n!}{2\pi i} \oint_{\mathcal{C}} \frac{z^{n}e^{-z}}{(z-x)^{n+1}} dz$$
(23)

with C centered around x. Combining it with  $L_n(x) = \frac{e^x}{n!} \frac{\mathrm{d}^n}{\mathrm{d}x^n} x^n e^{-x}$ , one has

$$L_n(x) = \frac{e^x}{2i\pi} \oint_{\mathcal{C}} \frac{z^n e^{-z}}{(z-x)^{n+1}} \mathrm{d}z$$
(24)

We inject this in the definition of the generating function, the countour is chosen such that |zt/(z-x)| < 1 to ensure convergence of the sum and to contain the x - t pole:

$$G(x,t) = \frac{e^x}{2i\pi} \sum_{n=0}^{\infty} \oint_{\mathcal{C}} \frac{(zt)^n e^{-z}}{(z-x)^{n+1}} dz = \frac{e^x}{2i\pi} \oint_{\mathcal{C}} \sum_{n=0}^{\infty} \left(\frac{zt}{z-x}\right)^n \frac{e^{-z}}{(z-x)} dz$$
(25)

$$= \frac{e^x}{2i\pi} \oint_{\mathcal{C}} \frac{1}{1 - \frac{zt}{z - x}} \frac{e^{-z}}{(z - x)} dz = \frac{e^x}{2i\pi(1 - t)} \oint_{\mathcal{C}} \frac{e^{-z}}{z - x/(1 - t)} dz$$
(26)

$$=\frac{e^x}{1-t}e^{-x/(1-t)} = \frac{e^{-xt/(1-t)}}{1-t}$$
(27)

3. [2] From 
$$\frac{\partial}{\partial t}G(x,t) = \sum_{n=0}^{\infty} (n+1)L_{n+1}(x)t^n = \frac{1-t-x}{(1-t)^2}G(x,t)$$
, we get  
 $(1-t)^2 \sum_{n=0}^{\infty} (n+1)L_{n+1}(x)t^n = (1-t-x)\sum_{n=0}^{\infty} L_n(x)t^n$ 
(28)

and equalling  $t^n$  coefficients gives

$$(n+1)L_{n+1}(x) - 2nL_n(x) + (n-1)L_{n-1}(x) = (1-x)L_n(x) - L_{n-1}(x)$$
(29)

and finally

$$(n+1)L_{n+1}(x) = (2n+1-x)L_n(x) - nL_{n-1}(x)$$
(30)

4. [2] From 
$$\frac{\partial}{\partial x}G(x,t) = \sum_{n=0}L'_n(x)t^n = \frac{-t}{1-t}G(x,t)$$
, we immediately get  
 $L'_n(x) - L'_{n-1}(x) = -L_{n-1}(x)$  (31)

Then, differentiating (30) gives

$$(n+1)L'_{n+1} = -L_n + (2n+1-x)L'_n - nL'_{n-1}$$
(32)

$$(n+1)(L'_{n+1} - L'_n) = -L_n - xL'_n + n(L'_n - L'_{n-1})$$
(33)

$$-(n+1)L_n = -L_n - xL'_n - nL_{n-1}$$
(34)

in which we have used (31); so that

$$xL'_{n}(x) = n(L_{n}(x) - L_{n-1}(x))$$
(35)

5. [1] From the definition of the generating function, we have  $L_n(x) = \frac{1}{n!} \frac{\partial^n G(x,t)}{\partial t^n}\Big|_{t=0}$ . For x = 0, it simplifies to  $L_n(0) = \frac{1}{n!} \frac{\partial^n}{\partial t^n} \frac{1}{1-t}\Big|_{t=0} = \frac{1}{n!} \frac{n!}{(1-t)^{n+1}}\Big|_{t=0} = 1$ .

6. [1] We have  $a_0 = 1$  and from (30), it is clear that

$$(n+1)a_{n+1} = -a_n \quad \Longrightarrow \quad a_n = \frac{(-1)^n}{n!} \tag{36}$$

7. [2] We obtain from (30) that

$$L_0(x) = 1, \quad 1! L_1(x) = -x + 1, \quad 2! L_2(x) = x^2 - 4x + 2, \quad 3! L_3(x) = -x^3 + 9x^2 - 18x + 6, \quad (37)$$

8. [1] Using the w(x) weighted scalar product definition and notation  $N_n$  for the norm, it follows from the lectures that

$$\int_0^\infty e^{-x} L_n(x) L_m(x) \mathrm{d}x = N_n \delta_{nm}$$
(38)

9. [2] We have

$$N_n = \int_0^\infty e^{-x} L_n(x) L_n(x) dx = \frac{1}{n!} \int_0^\infty L_n(x) \frac{d^n}{dx^n} (x^n e^{-x}) dx = \frac{(-1)^n}{n!} \int_0^\infty \frac{d^n L_n(x)}{dx^n} x^n e^{-x} dx$$
(39)

where we have used n times the integration by parts. Since  $L_n$  is a polynomial of order n,  $\frac{\mathrm{d}^n L_n}{\mathrm{d} x^n}$  is just the constant  $n!a_n = (-1)^n$  that we have computed. Finally,

$$N_n = \frac{1}{n!} \int_0^\infty x^n e^{-x} dx = \frac{n!}{n!} = 1$$
(40)

from the properties and definition of the Gamma function.

10. a) [1] We write 
$$a_n = \langle L_n, f \rangle_w = \int_0^\infty e^{-x} L_n(x) f(x) dx$$

b) [2] We proceed as for the computation of  $N_n$ .

$$a_{n} = \int_{0}^{\infty} e^{-(1+r)x} L_{n}(x) dx = \frac{1}{n!} \int_{0}^{\infty} e^{-rx} \frac{d^{n}}{dx^{n}} (x^{n} e^{-x}) dx = \frac{(-1)^{n}}{n!} \int_{0}^{\infty} \frac{d^{n} e^{-rx}}{dx^{n}} x^{n} e^{-x} dx = \frac{r^{n}}{n!} \int_{0}^{\infty} x^{n} e^{-(1+r)x} dx = \frac{r^{n}}{(1+r)^{n+1}}$$
  
We eventually obtain the identity  $e^{-rx} = \frac{1}{1+r} \sum_{n=0}^{\infty} \left(\frac{r}{1+r}\right)^{n} L_{n}(x).$ 

c) [1] simply use r = t/(1-t) giving t = r/(1+r) and use the definition of the generating function to recover the result.