

IV Beyond mean-field: fluctuations and scaling

→ Fluctuation correction to the saddle point

Back to our Ising functional; $B=0$:

$$\beta R[m(\vec{r})] = \int d\vec{r} \left[\frac{a_2}{2} m^2(\vec{r}) + \frac{a_4}{4} m^4(\vec{r}) + b (\nabla m)^2 \right]$$

and we account for small fluctuations around the most probable profile: $\delta m = m - m^*$

$$\frac{\delta R}{\delta m(\vec{r})} = 0 \quad \text{for } m^*(\vec{r}) : a_2 m(\vec{r}) + a_4 m^3(\vec{r}) - b \nabla^2 m = 0$$

$$\frac{\delta^2 R}{\delta m(\vec{r}) \delta m(\vec{r}')} = \delta(\vec{r} - \vec{r}') (a_2 + 3a_4 m^2 - b \nabla^2) \equiv K(\vec{r}, \vec{r}')$$

$$\Rightarrow \beta R[m(\vec{r})] \approx \frac{1}{2} \int d\vec{r} d\vec{r}' K(\vec{r}, \vec{r}') \delta m(\vec{r}) \delta m(\vec{r}') + \text{h.o.t}$$

We thus restrict to gaussian fluctuations; note that the kernel K may be viewed as a matrix [remember the advice: "be wise, discretize"], symmetric

$$Z = \exp(-\beta R[m^*]) \int \mathcal{D}m(\vec{r}) \exp \left\{ -\frac{1}{2} \int d\vec{r} d\vec{r}' K(\vec{r}, \vec{r}') \delta m(\vec{r}) \delta m(\vec{r}') \right\}$$

$$\frac{1}{\sqrt{\det K}}$$

$$\Rightarrow F = \underbrace{R[m^*]}_{\substack{\text{F}_{s.p.} \\ \text{mean-field}}} + \frac{1}{2} kT \underbrace{\log \det K}_{\text{Tr } \log K}$$

In a homogeneous system, $K(\vec{r}, \vec{r}') = K(\vec{r} - \vec{r}')$ is invariant by translation (\sim circulant matrix): diagonalized by a basis of plane waves \rightarrow go to Fourier. Imagine indeed K is a circulant matrix

$$\hat{K}(\vec{q}) = \sum_j K_{ij} e^{i\vec{q} \cdot (\vec{r}_i - \vec{r}_j)}$$

does not depend on i , hence notation

this also means $\sum_j K_{ij} e^{-i\vec{q} \cdot \vec{r}_j} = \hat{K}(\vec{q}) e^{-i\vec{q} \cdot \vec{r}_i}$

$\hat{K}(\vec{q})$ eigensalue \rightarrow eigenvector, one for each \vec{q} , (and \vec{q} discretized)

Here: $\hat{K}(\vec{q}) = \int d\vec{r}' K(\vec{r}, \vec{r}') \exp [i\vec{q} \cdot (\vec{r} - \vec{r}')] = \int d\vec{r}' \delta(\vec{r} - \vec{r}') (a_2 + 3a_4 m^2 - b \nabla'^2) e^{i\vec{q} \cdot (\vec{r} - \vec{r}')} = \int d\vec{r}' \delta(\vec{r} - \vec{r}') (a_2 + 3a_4 m^2 + b q^2) e^{i\vec{q} \cdot (\vec{r} - \vec{r}')} = a_2 + 3a_4 m^2 + b q^2 \equiv b (\beta^{-2} + q^2)$

We need here to remember: $\vec{q} = \frac{2\pi}{L} (n_x, n_y, n_z)$ say in a 3d cubic box
 $\text{Tr} \Leftrightarrow \sum_{\vec{q}} \Leftrightarrow \sum_{n_x, n_y, n_z} \Leftrightarrow L^3 \int \frac{d\vec{q}}{(2\pi)^3} \Leftrightarrow V \int \frac{d\vec{q}}{(2\pi)^d}$ in general

$$\Rightarrow \underline{F = F_{D.P.} + \frac{1}{2} kTV \int \frac{d\vec{q}}{(2\pi)^d} \log(\xi^{-2} + q^2)}$$

$\xi \rightarrow$ omitted

There is an upper cutoff: $q < 1/a$, as a signature of the underlying lattice

Define $t \equiv \frac{T-T_c}{T_c}$, we have seen that

$$\xi^{-2} \propto |t|, \quad \text{at mean-field level (i.e. } \nu = 1/2)$$

We also know that $F_{D.P.}$, the mean-field term, yields $\alpha = 0^{(*)}$ for specific heat

$$c \equiv -T \left. \frac{\partial^2 F}{\partial T^2} \right|_B$$

and since $\partial_T F$ does not exhibit any singularity, what matters for the singular contribution to c is

$$c_{\text{sing}} = -k_B \frac{\partial^2 BF}{\partial t^2}$$

The fluctuation terms thus give a correction to c in

$$\left| \int \frac{d\vec{q}}{(2\pi)^d} \frac{1}{(\xi^{-2} + q^2)^2} \right.$$

integral convergent at small q but is in q^{d-5}
hence diverges for $d > 4$, converges $d < 4$

the integral has dimension $(\text{length})^{4-d}$, changes behaviour at $d=4$

$d > 4$: diverges at large $q \sim \frac{1}{a}$, hence $\propto a^{4-d}$

$d < 4$: converges at large q (also at small q) and q can be rescaled by $\xi^{-1} \Rightarrow \propto \xi^{4-d}$

Thus for $d > 4$, the correction is finite and does not alter the mean-field conclusion.

For $d < 4$, the correction $\rightarrow \infty$ for $T \rightarrow T_c$ (since $\xi \rightarrow \infty$): the approach is not self-consistent, mean-field is invalid; fluctuations destroy mean-field prediction

(*) $a_2 m^x + a_4 (m^x)^3 = 0$; $a_4 m^{x*2} = -a_2$

$$F_{D.P.} = \frac{1}{2} a_2 (m^x)^2 + \frac{1}{4} a_4 (m^x)^4 \propto \frac{(a_2)^2}{a_4}$$

and $a_2 = \tilde{a}_2 \times (T-T_c) = \tilde{a}_2 T_c t$

$$\propto t^2 \quad \text{for } t < 0$$

$$c_{\text{sing}}^{(m)} = 0 \quad T > T_c$$

$$\propto \tilde{a}_2^2 / a_4 \quad T < T_c$$

→ **Ginzburg criterion**

Since $\frac{c_{\text{fluct connection}}}{c_{\text{mean-field}}} \propto \xi^{4-d} = \left(\frac{\xi_0}{\xi_G}\right)^{4-d}$; $\xi_G \equiv$ Ginzburg length

In some systems, ξ_G is very large, and $\xi \ll \xi_G$ except very close to T_c . For superconductors in particular, we have $\xi \approx \xi_G$ for $|t| < 10^{-16}$, which is beyond reach → we will thus see mean-field critical exponents in such a system. This behavior is exceptional. Usually, ξ_G is microscopic, and mean-field behavior is not observed.

→ **Summary on fluctuations**

For the Ising model, $d=4$ corresponds / defines the **upper critical dimension**, d_u (for other models, d_u may be $\neq 4$).

- $d > d_u$: mean-field critical exponents are exact (but non-universal quantities, such as T_c , are not)
- $d_{\text{lower}} < d < d_u$: fluctuations are strong enough to invalidate mean-field but not sufficient to destroy order.
 - ↳ 1 for discrete
 - ↳ 2 for continuous symmetry
- $d < d_{\text{lower}}$: fluctuations destroy the ordered phase

→ **Scattering and fluctuations: experimental aspects**

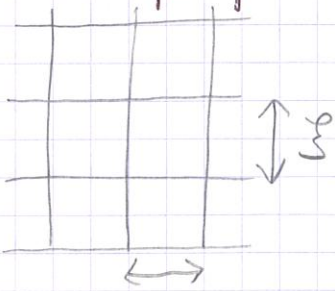
Scattering exp probe fluctuations at a scale $\lambda \propto 1/l$

Scattering light	↔	positional order (atomic density)	} Chandler 7.5
e^-	↔	charge " (charge ")	
neutrons	↔	magnetic "	

The key object is the structure factor $S(\vec{k}) = \frac{1}{N} \left\langle \sum_{i,j} e^{i\vec{k} \cdot (\vec{r}_i - \vec{r}_j)} \right\rangle$

→ Beyond mean-field: the scaling hypothesis

Scaling arguments can be very powerful. For instance, we found a fluctuation correction to the mean-field free energy in $V kT \int d\vec{q} \ln[\xi^{-2} + q^2]$ & $\frac{V kT}{\xi^d}$



Partition indeed the system in boxes of size ξ , and assume $\xi \gg a$ (microscopic length). The different boxes are uncorrelated and by extensivity

$$F_{\text{fluct}} \propto \frac{V}{\xi^d} \underbrace{F_{\text{box}}}_{kT f(t, B)}, \text{ regular}$$

We should then compare this contribution to

the mean-field $F_{\text{m.f.}} = F_{\text{s.p.}} \propto t^2$ (we found $\alpha = 0$)

Mean-field holds provided $t^2 \gg \xi^{-d} \propto t^{\nu d}$ (with $\nu = 1/2$) $\propto t^{d/2}$

$$\Rightarrow d/2 > 2 \quad \text{i.e.} \quad d > d_{\text{upper}} = 4$$

We now explore further the consequences of having ξ large (close to a 2nd order transition). Consider the free energy density of magnetic system (its singular contribution)

$$f_{\text{sing}} = -\frac{\ln Z}{V} = \frac{1}{\xi^d} \tilde{f}\left(t, B, \frac{a}{\xi}\right) \quad \text{only depends on dimensionless quantities}$$

Microscopic details matter, through a . Yet, for T close

enough to T_c , ξ very large and those details should become irrelevant, $\frac{a}{\xi} \rightarrow 0$

and \tilde{f} should be well behaved in this limit. Hence

$$f_{\text{sing}} = \frac{1}{\xi^d} \tilde{f}(t, B)$$

Next assumption: the info can be compressed down to a form where every q^{th} is expressed in its relevant scale. For B , this scale is m^{ξ} with $m \propto |t|^{\beta}$, hence

$$f_{\text{sing}} = \frac{1}{\xi^d} g\left(\frac{B}{|t|^{\beta \xi}}\right)$$

→ For the equation of state of liquids, or p vs T , see Guggenheim's plot.

Consequences

We can assume that $g(0)$ is finite, since $B=0$ well behaved. Then

$$f_{\text{sing}} \propto \xi^{-d} \quad \text{and also} \quad \propto |t|^{2-\alpha}$$

$$\nu d = 2 - \alpha$$

IPa school on disorder in complex systems (2022) Phase transitions

6

Likewise: $\chi \propto |t|^{-\gamma} \propto \frac{\partial^2 f}{\partial B^2} \propto \xi^{-d} |t|^{-2\beta\delta}$

$\Rightarrow -\gamma = \nu d - 2\beta\delta$

These are scaling relations, true for all universality classes. Among the 6 exponents $\alpha, \beta, \delta, \nu, \gamma, \nu$, only 2 are independent. We can also show

$(1+\delta)\beta = \nu d \rightarrow m = -\partial_B f \propto \xi^{-d} |t|^{-\beta\delta} \propto |t|^{+\beta}$ at $B=0$
 $\nu d - \beta\delta = \beta$

At this point, we only have 3 scaling relations: we miss one, following from correlated func.

→ An interesting prediction for the correlation length. We know that $\xi \propto |t|^{-\nu}$ for $B=0$.

What about ξ for $B \neq 0$ but $T=T_c$, that should diverge for $B \rightarrow 0$?

Scaling ansatz:

$\xi = |t|^{-\nu} \psi(B/|t|^{\beta\delta}) \rightarrow$ called the gap exponent
 $= B^{-\nu/\beta\delta} \tilde{\psi}\left(\frac{B}{|t|^{\beta\delta}}\right)$ ie $\psi(x) \equiv x^{-\nu/\beta\delta} \tilde{\psi}(x)$

The value of ξ is finite for $B \neq 0$ and $t=0$, thus

$\xi \propto B^{-\nu/\beta\delta}$ @ T_c . Diverges when $B \rightarrow 0$, as expected

From Onsager 2d solution $\frac{\nu}{\beta\delta} = \frac{1}{\frac{8}{15}} = \frac{8}{15} \approx 0,53$, non-trivial result.

NB Mathematically speaking, we are playing here with homogeneous functions, s.t.

$f(\lambda^a x, \lambda^b y) = \lambda f(x, y) \Rightarrow f(x, y) = x^{1/a} f(1, y x^{-b/a})$

For instance: $\xi = |t|^{-\nu} \psi\left(\frac{B}{|t|^{\beta\delta}}\right) = |t|^{-\nu} \tilde{\psi}\left(\frac{B}{|t|^{\beta\delta}}\right)$

thus here $a = -1/\nu$, $b/a = \beta\delta$

which are the homogeneity indices of the function ψ

→ Finite-size scaling: turning a drawback into an advantage

Computer simulations are always with a finite-size system (L), and close to T_c , $L \ll \xi$ necessarily \rightarrow pb for studying a bulk property.

Solution? A bona fide scaling assumption: close to T_c , the only relevant length is ξ .

Consider $\chi(t, L)$ at $B=0$. We know that $\chi(t, \infty) \propto |t|^{-\gamma}$, but $\chi(t, L)$!

Scaling assumption: $\frac{\chi(t, L)}{\chi(t, \infty)} = \text{dimensionless function of } t \text{ and } L$
 $= \varphi\left(\frac{L}{\xi_\infty(t)}\right); \quad \xi_\infty(t) \propto |t|^{-\nu}$

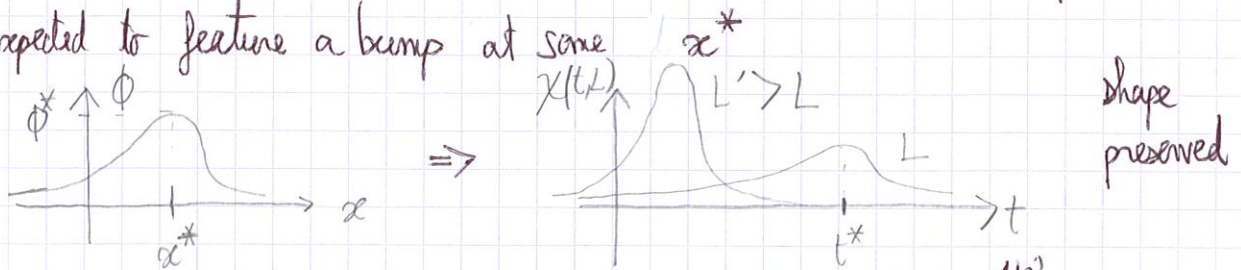
$$\Rightarrow \chi(t, L) = |t|^{-\delta} \varphi(L |t|^\nu)$$

$$= L^{\delta/\nu} \psi(L |t|^\nu) \quad \varphi(x) = x^{\delta/\nu} \psi(x)$$

We have been a bit sloppy with sign of t , and one should distinguish $t < 0$ from $t > 0$
 To include both $t > 0$ and $t < 0$ in a relevant expression, we write

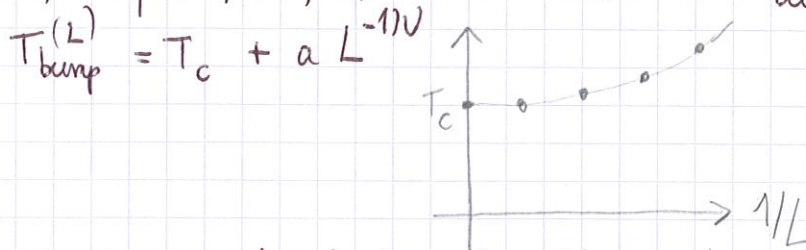
$$\chi(t, L) = L^{\delta/\nu} \phi(\pm L^{1/\nu} t)$$

Because $\chi(t, \infty) \propto |t|^{-\delta}$, we have $\phi(x) \propto |x|^{-\delta}$ for $x \rightarrow \infty$ or $-\infty$
 ϕ is expected to feature a bump at some x^*



Bump of $\chi(t, L)$ at $t^* = x^* L^{-1/\nu} \xrightarrow{L \rightarrow \infty} 0$
 Height " " $\propto L^{\delta/\nu}$

In practice, we plot $\chi(T, L)$ vs T . Look at $T_{\text{bump}}^{(L)}$ vs L



Once T_c is found, we get ν from this plot, and δ/ν from the height of χ (its maximum value, vs L).

Criticality is not encoded in $\varphi(0)$ nor $\varphi(\infty)$ but some $\varphi(x^*)$ where x^* is the max of ϕ

→ Correlation functions and self-similarity

Scaling ansatz: $G(\vec{r}, t) = \xi^a g(r/\xi) = r^a h(r/\xi)$

that we can rewrite, from the known behavior at T_c :

$$G(\vec{r}, t) = \frac{1}{r^{d-2+\eta}} g\left(\frac{r}{\xi}\right); \quad g(0) \text{ finite}$$

system is self-similar, up to scale ξ
 (of critical opalescence).

At T_c : scale invariance / self-similarity i.e. $G(\lambda r) = \lambda^a G(r)$

Meaning: if a snapshot of a critical system is blown up by a factor λ , then apart from a change of contrast (multiplication by λ^a), the new snapshot is statistically equivalent to original. Hallmark of fractal geometry

We now have the final scaling relation, from $\chi \propto \int G(\vec{r}) d\vec{r}$
 $\int d\vec{r} G(\vec{r}) = \int d\vec{r} \frac{1}{s^{d-2+\eta}} g(r/s) \propto \frac{s^d}{s^{d-2+\eta}} \propto s^{2-\eta} \propto |t|^{\nu(\eta-2)}$
 $\propto |t|^{-\delta}$

$$\Rightarrow \delta = \nu(2-\eta)$$

Check with \otimes Onsager solution in 2d: $\frac{7}{4} = 1 \left(2 - \frac{1}{4}\right)$
 \otimes mean-field: $1 = \frac{1}{2} (2 - 0)$