

Does wave breaking really always lead to such a simple shock structure? In general the answer is no, but one can argue that in the presence of viscosity this is indeed the case. (15)

For the traffic equations let's slightly modify the model in which instead  $Q(\rho) \rightarrow Q(\rho) - v \rho_x$  (with  $v > 0$ ) this means that if a driver sees an increasing density ahead he will slow down. In this case the conservation equation becomes =

$$S_t + [Q(\rho) - v \rho_x]_x = 0$$

leading to  $S_t + c(\rho) \rho_x = v \rho_{xx}$  where  $c(\rho) = Q'(\rho)$  as usual.

this is called an advection-diffusion equation =  $c(\rho) \rho_x$  is the advective part and  $v \rho_{xx}$  the diffusive term.

nonlinear

indeed without the advective term one has a simple heat equation:  $S_t = v \rho_{xx}$  which is THE diffusion equation

note that the term  $v \rho_{xx}$  is indeed a viscous term: (i) it is physical intuitive that it will tend to damp strong fluctuations but (ii) it can also be seen by studying the propagation of small perturbations:

$$g(x,t) = g_0 + g_1(x,t) \quad |g_1| \ll g_0 \quad c(g_0) = c_0$$

$$\text{one has } g_{1t} + c_0 g_{1xx} = v g_{1xx}. \quad \text{If one look for plane wave solutions of the form:}$$

$$g_1 = A e^{i(kx - \omega t)} \quad \text{one gets}$$

$$\omega = c_0 k - i v k^2 \Rightarrow \text{hence}$$

$$g_1(x,t) = A e^{i k (x - \omega t)} e^{-v k t}$$

damping term. Note that  $v$  has to be positive otherwise = instability ( $g_1$  diverges). But this was clear from the beginning - ( $Q$  should  $\downarrow$  when  $\rho_x > 0$ )

one aims at describing a shock structure propagating at constant velocity  $U$  for the new equation (which would be the  $V \neq 0$  version of the stupid shock of pages 13 & 14 if everything goes ok).

one looks for a steady profile  $s = g(x)$  with  $X = x - Ut$ . Then the eq. reads:

$$[-U + c(g)]g_x = Vg_{xx} \xrightarrow[\text{integral}]{\text{first}} -Ug + Q(g) + A = Vg_x \quad (A = \text{constant of integration})$$

using  $\int dx = \int \frac{dg}{g_x}$  one can compute, or least formally, the shape of  $g(x)$ . But first a remark = One wants an asymptotic profile such that



$$\lim_{x \rightarrow \pm\infty} g(x) = s_{2/1}$$

one thus has  $-Ug_i + Q(g_i) + A = 0 = -Ug_2 + Q(g_2) + A$

hence =

$$U = \frac{Q(g_2) - Q(g_i)}{g_2 - g_i}$$

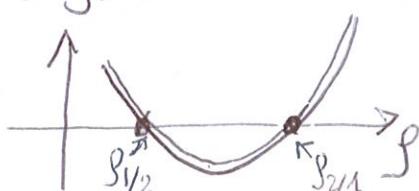
this is the shock velocity determined page (13) !

shape  $g(x)$  = one has  $\frac{X}{V} = \int \frac{dg}{Q(g) - Ug + A}$

$s_1$  and  $s_2$  are zeros of  $Q(g) - Ug + A$  hence as  $g \rightarrow s_{2/1}$ ,  $X$  diverges and tends to  $\pm\infty$  as required. Let's consider discuss the signs in the case where  $c'(g) > 0$  (which is the case considered in pages B-14 (actually starting from the end of page 9) and does not corresponds to the situation in traffic flows -)

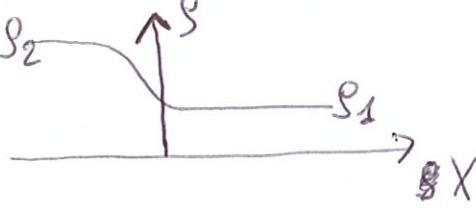
$v > 0$ , then  $\text{sign}(g_x) = [\text{sign}(Q(g) - Ug + A)]$   
[between  $s_1$  and  $s_2$ ]

~~if  $s_1 < s_2$~~  then since  $c'(g) = Q''(g) > 0$ ,  $Q$  is convex and one has:  $Q(g) - Ug + A$



$Q(g) - Ug + A < 0$  between the roots

thus  $S_x < 0$  and one must have  $S_1 > S_2$  for deferring the shock which looks like:  $S_2$



and indeed, this is the physically expected configuration for a shock when  $c(g) > 0$ .

Finally it is clear that if  $S_1$  and  $S_2$  are kept fixed (so that  $\nu$  and  $A$  are fixed) a change in  $V$  can be absorbed by a change ~~of~~ in the  $X$  scale.

One has:  $S = F(X/\nu)$  where  $F$  depends on  $S_1$  and  $S_2$   
 but not on  $V$  = as  $V \rightarrow 0$  the profile is compressed in the  $X$  direction and tends to a step function having all the characteristics computed previously for  $V=0$ . The shock structure is only a special solution of  $S_t + c(g)S_x = \nu S_{xx}$ , but from it we might expect in general that when  $V \rightarrow 0$  the solution of this eq. tends to the one of  $S_t + c(g)S_x = 0$ .

However in some cases the shock structure is not resolved by viscosity, but by dispersion effects instead. This is the case for the ~~KdV~~ eq for instance where:

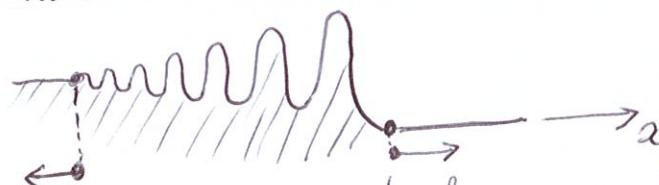
$$S_t + c(g) S_x + \nu S_{xx} = 0$$

(here the sign of  $V$  is of great importance:  
 $\omega = c(g)b - \nu k^3$ )

this has been studied a lot, and for KdV, when  $c(g) = g$  an initial condition:



leads to:



this is called a dispersive shock wave. Occurs in tidal bore for instance. Let's now study the combined effects of nonlinearity and dispersion.

$$\text{are start with } \rho_t + C(\rho) \rho_x + \gamma \rho_{xxx} = 0$$

weak nonlinearity  
 $C(\rho) \approx C_0 + C_1 \rho$

weak dispersive effect. At least, the 1st one can think of.

$$\begin{cases} \xi = x - ct \\ \tau = t \end{cases} \rightarrow \begin{cases} \partial_x = \partial_\xi \\ \partial_t = -c \partial_\xi + \partial_\tau \end{cases} \rightarrow -C_0 \rho_\xi + \rho + (C_0 + C_1 \rho) \rho_\xi + V \rho_{\xi\xi\xi} = C$$

$$\rightarrow \rho_\tau + C_1 \rho \rho_\xi + V \rho_{\xi\xi\xi} = 0$$

Note = one can change the sign of  $V$  by doing  $\xi \rightarrow -\xi$ ,  $\rho \rightarrow -\rho$ . So let's assume that  $V > 0$ .

then we defines:  $t = \alpha \tau$  this leads to =

$$\begin{cases} t = \alpha \tau \\ \chi = \beta \xi \\ \rho = \alpha u \end{cases} \quad \alpha \delta u_t + C_1 \beta \delta^2 u u_x + V \beta^3 \delta u_{xxx} = 0$$

$$\text{take } \alpha = 1, C_1 \beta \delta = 1 \text{ and } V \beta^2 = 1 \rightarrow \boxed{u_t + u u_x + u_{xxx} = 0}$$

KdV equation first

derived in the study of shallow water waves in 1895. Here the eq. is written in dimensionless form.

let's do the same as we did for the Burger's equation = look for solutions depending on  $x - vt$  only:  $u(x, t) = u(x - vt)$ .

then one gets

$$-V u' + u u' + u''' = 0$$

$$\text{first integral: } -V u + \frac{u^2}{2} + u'' = C_1$$

multiply by  $u'$  and integrate again =

$$-V \frac{u^2}{2} + \frac{u^3}{6} + \frac{1}{2} u'^2 = C_1 u + C_2$$

this is of the form

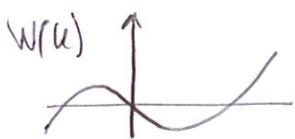
$$\boxed{\frac{u'^2}{2} + W(u) = C_2}$$

$$\downarrow$$

$$\boxed{\frac{u^3}{6} - V \frac{u^2}{2} - C_1 u}$$

I assume  
hence path  
that  $V > 0$ -change  
the sign of  $V$  by  
changing the sign of  $t$

if  $a > 0$  one has:



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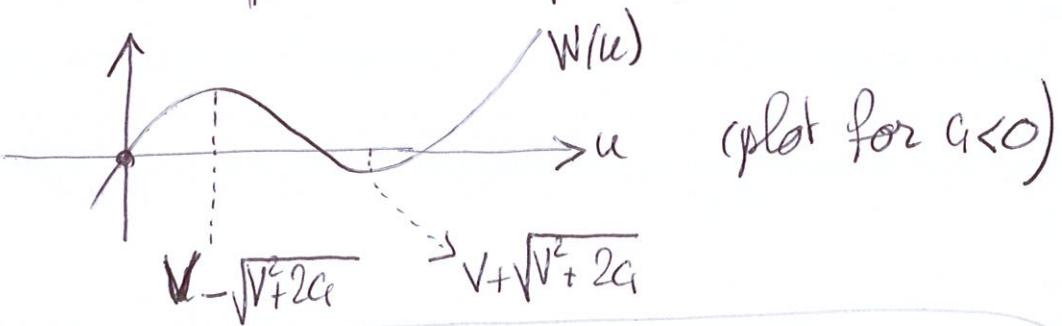
if  $a < 0$  one has



for having a bounded solution one needs that  $W(u)$  has a local minimum =  $W'(u) = \frac{u^2}{2} - Vu - a = 0$  one has real roots iff  $V^2 + 2a > 0$   $\leftarrow$  this will be assumed as verified henceforth

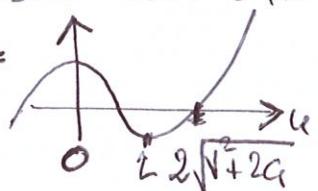
then  $W'$  cancels for  $u = V \pm \sqrt{V^2 + 2a}$

one thus has:



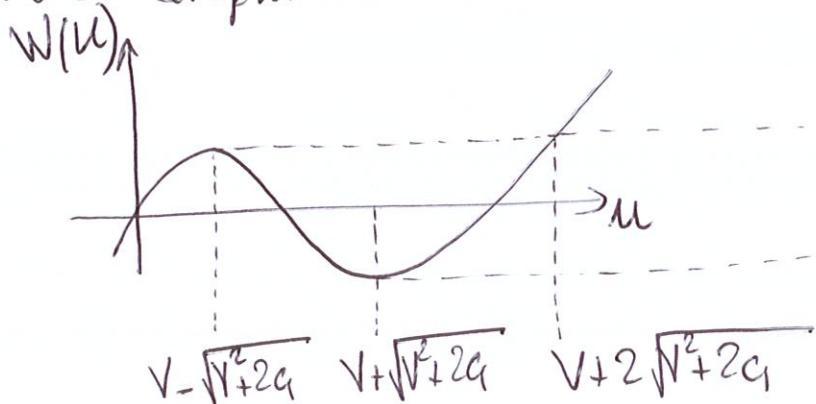
by a change of variable  $u = v(x - vt) + V - \sqrt{V^2 + 2a}$  one can work in a configuration with =

INUTILE



but this is not necessary.

a tedious computation shown that one has (of page 20)



$$\textcircled{+} \frac{1}{3}(V^2 + 2a)^{3/2} - Va - \frac{V^3}{3}$$

$$\textcircled{-} \frac{1}{3}(V^2 + 2a)^{3/2} - Va - \frac{V^3}{3}$$

so,  $c_2$  should be in this range for having a bounded solution -

side computation = let's denote  $u_0 = V - \sqrt{V^2 + 2G}$  the local maximum

$$W(u_0) = \frac{1}{6} u_0^3 - \frac{V}{2} u_0^2 - Gu_0^* = \frac{u_0}{3} \left( \frac{u_0^2}{2} - \frac{3}{2} Vu_0^* - 3G \right) = \frac{u_0}{3} \left( -\frac{V}{2} u_0 - 2G \right) =$$

$$= -\frac{V}{3} \frac{u_0^2}{2} - \frac{2}{3} Gu_0 = -\frac{u_0}{3} (V + 2G) - \frac{VG}{3} = -\frac{1}{3} (V - \sqrt{V^2 + 2G}) (V + 2G) - \frac{VG}{3}$$

$$= +\frac{1}{3} (V^2 + 2G)^{3/2} - VG - \frac{V^3}{3}$$

$V + 2G$

Look for the solution of  $W(u) = W(u_0)$ .  $u_0$  is a double solution, so this equation, which reads  $u^3 - 3Vu^2 - 6Gu = 2(V^2 + 2G)^{3/2} - 6VG - 2V^3$

can be written under the form:  $(u - u_0)^2(u - u_M) = 0$

$$\Leftrightarrow (u^2 - 2u_0(u + u_0^2))(u - u_M) = 0$$

$$\Leftrightarrow u^3 + u^2(-u_M - 2u_0) + u(u_0^2 + 2u_0 u_M) = u_M u$$

$2Vu_0 + 2G$        $2Vu_0 + 2G$

$$\Leftrightarrow \boxed{u^3 - u^2(u_M + 2u_0) + u(2(u_M + V)u_0 + 2G) = 2(Vu_0 + G)u_M}$$

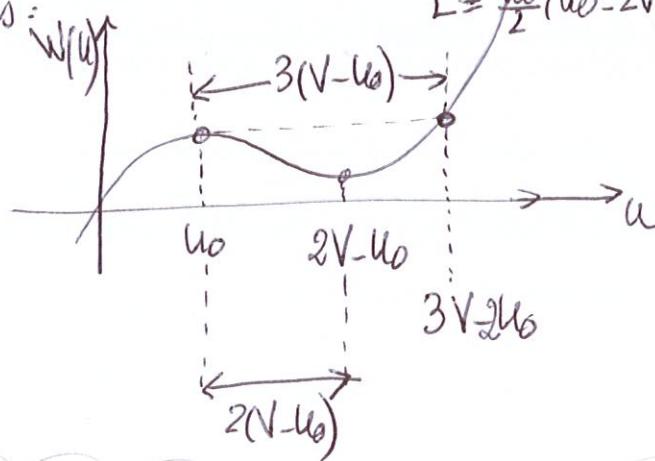
Comparing the 2 framed eqs one gets

$$u_M = V + 2\sqrt{V^2 + 2G}$$

this value makes it possible to match the coeffs of all the powers of  $u$  in the framed eqs.

$$u_0 = V - \sqrt{V^2 + 2G}$$

other parametrization = It is more appropriate to define  $u_0$  as a parameter. Then  $G = \frac{1}{2} (V - u_0)^2 - \frac{V^2}{2}$  and  $\sqrt{V^2 + 2G} = V - u_0$  and one has:



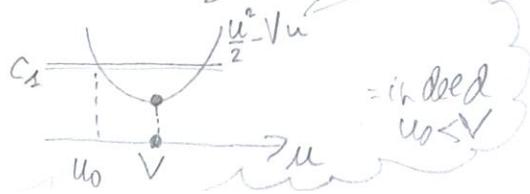
and the condition

$$V^2 + 2G > 0$$

is always fulfilled.

one has also  
always  $V > u_0$

of course  $W'(u) = 0$  reads  $\frac{u^2}{2} - Vu = c_1$   
so, one has:

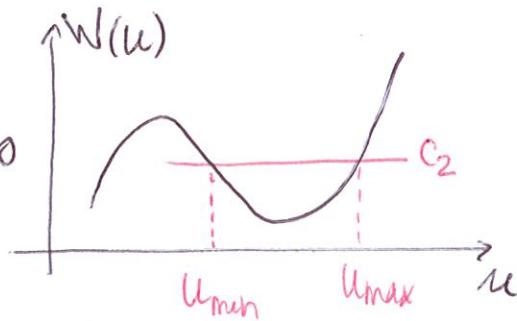


(but  $u_0$  can be  $> 0$  or  $< 0$ )

(21)

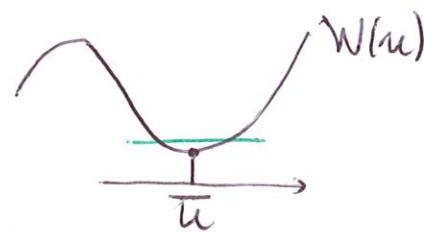
so for given  $C_2$  one has:

$u$  has non linear oscillations between  $u_{\min}$  and  $u_{\max}$



\* when  $C_2$  is close to the minimum

$$\begin{cases} W(u) = \frac{u^3}{6} - \frac{Vu^2}{2} - Cu \\ W'(u) = \frac{u^2}{2} - Vu - C = \text{zero at } \bar{u} \\ W''(u) = u - V \end{cases}$$



close to  $\bar{u}$  one writes  $W(u) \approx W(\bar{u}) + \frac{1}{2}(u-\bar{u})^2 W''(\bar{u})$

then the eq.  $\frac{u'^2}{2} + W(u) = C_2$  leads (after derivation) to  $= u'' + (u-\bar{u}) W''(\bar{u}) = 0$

set  $u(x-Vt=\xi) = \bar{u} + u^{(1)}(\xi)$  where  $u^{(1)}(\xi) \propto e^{\pm i \sqrt{W''(\bar{u})} \xi}$

this is of the form  $\pm i(kx - \omega t)$  with  $k = \sqrt{W''(\bar{u})} \rightarrow k^2 = \bar{u} - V$

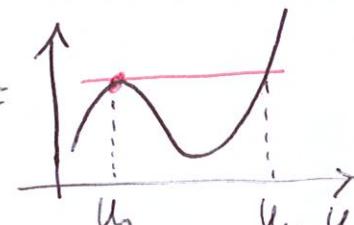
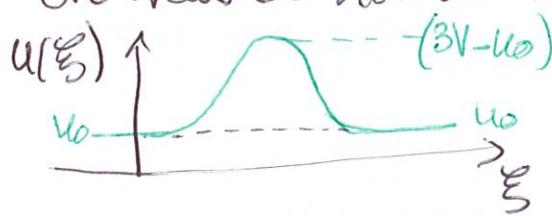
$$\text{and } \omega = \sqrt{V W''(\bar{u})} = \sqrt{V k}$$

since  $V = \bar{u} - k^2$  the dispersion

relation reads  $\omega = (\bar{u} - k^2)k$  as expected.

\* more interesting = when  $C_2$  is at the maximum:

then one has a soliton solution =



$$\text{one has } \frac{u'^2}{2} + W(u) = W(u_0) \rightarrow \frac{u'^2}{2} = W(u_0) - W(u) = \frac{1}{6} (u - u_0)^2 (u_M - u)$$

$$\text{writing } u = u_0 + \vartheta(\xi) \rightarrow \frac{\vartheta'^2}{2} = \frac{1}{3} \vartheta^2 (v_M - v) \text{ where } v_M = u_M - u_0 \\ = 3(V - u_0)$$

$$\text{hence } \frac{d\vartheta}{d\xi} = \pm \frac{\vartheta}{\sqrt{3}} (v_M - v)^{1/2}$$

$$\text{let's consider the case where } \frac{dv}{d\xi} > 0 = \frac{d\xi}{\sqrt{3}} = \frac{(\pm) d\vartheta}{\vartheta (v_M - v)^{1/2}}$$

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one writes  $v = \frac{v_m}{w^2} \rightarrow dv = -\frac{2v_m dw}{w^3}$

and  $\frac{d\xi}{\sqrt{3}} = (\pm) \frac{-2v_m dw/w^3}{\frac{v_m^{3/2}}{w^2} (1 - \frac{1}{w^2})^{1/2}} = -(\pm) \frac{2dw}{\sqrt{v_m} \sqrt{w^2 - 1}}$

then  $w = \operatorname{ch} \theta \quad dw = \operatorname{sh} \theta d\theta = (\mp) \sqrt{1-w^2} d\theta \quad \text{with } \begin{cases} - & \text{when } D < \\ + & \text{when } D > \end{cases}$

hence one gets  $\frac{d\xi}{\sqrt{3}} = \frac{2 d\theta}{\sqrt{v_m}} \rightarrow \theta = \frac{\sqrt{v_m/3}}{2} \xi = \frac{\sqrt{V-u_0}}{2} \xi \quad \xrightarrow{\text{def}} \xi = Vt$

hence = 
$$\boxed{u(\xi) = u_0 + \frac{3(V-u_0)}{\operatorname{ch}^2 \left[ \frac{\sqrt{V-u_0}}{2} \xi \right]}}$$

depth way = one writes  $u = u_0 + \theta$

then  $W(u) = \frac{u^3}{6} - \frac{\sqrt{u^2}}{2} - \frac{u_0}{2}(u_0 - 2V)u \quad \left[ \text{using } a = \frac{u_0}{2} (u_0 - 2V) \right]$

and simple manipulations show that

$$W(u) - W(u_0) = \frac{v^3}{6} + \frac{v^2}{2}(u_0 - V)$$

then the eq.  $\frac{u'^2}{2} + W(u) = W(u_0)$  reads

$$\boxed{v'^2 + \frac{v^3}{3} + (u_0 - V)v^2 = C}$$

and there one looks for a solution

of the type  $v = \frac{a}{\operatorname{ch}^2(B\xi)} \rightarrow v' = -2aB \frac{\operatorname{sh}(B\xi)}{\operatorname{ch}^3(B\xi)}$

and plugging this back in the framed equation yields

$$4a^2 B^2 \frac{\operatorname{sh}^2}{\operatorname{ch}^5} + \frac{a^3}{3 \operatorname{ch}^6} + \frac{a^2 (u_0 - V)}{\operatorname{ch}^4} = 0$$

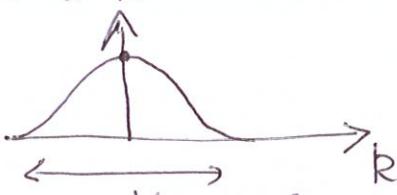
$$4a^2 B^2 \frac{\operatorname{sh}^2}{\operatorname{ch}^5} + \frac{a^3}{3} + a^2 (u_0 - V) \operatorname{ch}^2 \xrightarrow{(ch^2 - 1)} \begin{cases} B^2 = \frac{V - u_0}{4} \\ a = 12B^2 = 3(V - u_0) \end{cases}$$

on retrouve bien sûr la  
formule encadrée !

~~note = V < u\_M - u\_0~~

## hand-waving argument

the dispersion relation  $\omega = \omega_0 k - k^3$  gives the phase velocity  $v_p \approx \omega_0 k$  for one soliton where a Fourier transform (of  $u(x) - u_0$ ) =



$\sim 1/L$  where  $L$  is the (yet unknown) width of the soliton.

\* usually  $\neq k$ 's have  $\neq v_p \Rightarrow$  spreading.

this spreading is compensated by van der waals

$$\text{a given } R \quad v_p \approx \omega_0 + (u_M - k^2)_{\text{hyp}}$$

these 2 effects should compensate  $\Rightarrow$  (ad hoc description)  
of NL effect

$$[u_M \sim R^2]_{\text{hyp}} \sim 1/L^2$$

relies on the argu  
ment that soliton  
moves without changing its shape]

$\hookrightarrow$  note = exact result

$$S_{\text{exact}} \frac{e^{ikx}}{R} = \frac{\pi k / \beta}{\sinh(\frac{\pi k}{2\beta})}$$

so

$$S_{\text{exact}} e^{ikx} (u - u_0) = \frac{3 \sqrt{\omega_0} \pi k / 2}{\sinh(\frac{\pi k}{\sqrt{\omega_0}})}$$

← notation

note that  $u_M > 0 =$   
where the sign of dispersion  
different ( $\omega = \omega_0 k - k^3$ )  
then  $u_M < 0$

\* real space  $\Rightarrow$   $\exp[-\tilde{k}(x-vt)]$  since in this region the soliton is a small perturbation of the background, one can perform a linear expansion similar to what is done for  $e^{i(kx-wt)}$

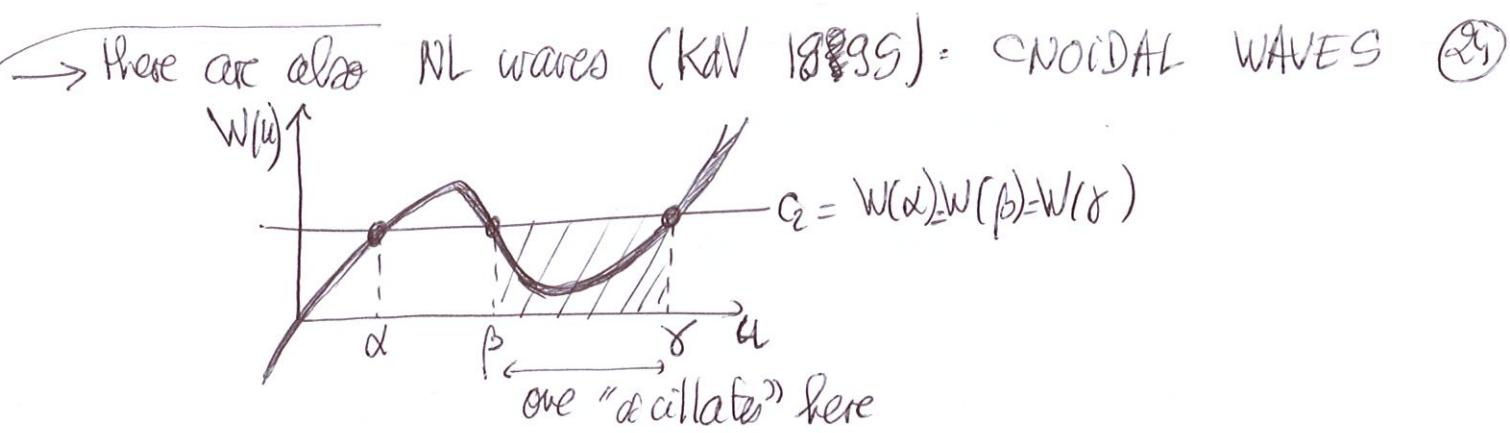
$$\text{hence } \tilde{k} \leftrightarrow -ik \quad -iw \leftrightarrow \tilde{V} \tilde{k} \quad \text{and } V = \frac{-iw(k=i\tilde{k})}{\tilde{k}}$$

$$\text{here } \omega(k) = \omega_0 k - k^3 \text{ this leads to } \left\{ \begin{array}{l} V = -i \frac{(\omega_0 i \tilde{k} + i \tilde{k}^3)}{\tilde{k}} \\ = \omega_0 + \tilde{k}^2 \end{array} \right.$$

↳ of course  $\tilde{k} = 1/L$  and one gets

$$V \sim \omega_0 + 1/L^2$$

\* gathering the two evaluations one gets =  $\left\{ \begin{array}{l} L \sim \frac{1}{\sqrt{\omega_0}} \\ u_M \sim V - \omega_0 \end{array} \right.$   
(in accordance with the exact result)



one has  $\frac{u'^2}{2} = C_2 - W(u) =$  it's a 3<sup>rd</sup> order polynomial ~~if~~ can be written  
 $> 0$  in the allowed region  $\Theta S = \frac{1}{6}(u-\alpha)(u-\beta)(\gamma-u)$

Then  $\int \frac{du}{\sqrt{3}} = \int_{\beta}^u \frac{du}{(u-\alpha)(u-\beta)(\gamma-u)}$  →  $u(\xi)$  is an elliptic ~~integral~~ function.  
 these are denoted as cn, sn and dn  
 hence one speaks of "cnoidal waves".

When  $C_2$  changes one goes from sinusoidal, to cnoidal and then to a soliton.

Ubiquity of KdV =

it is a very natural PDE for who aims at describing both non linearity and dispersion - Start from  $\omega = ck$ , and then try to add these two effects =

$$c \rightarrow c_0 + \frac{C_1}{k} \left( \text{wave amplitude} = u \right) + \frac{C_2}{k^2} \nu R$$

of course  $k^2 = \frac{\omega^2}{c^2}$   
 the wavelength matters, no its "sign"!

this leads to =

$$\omega = c_0 k + u k + \nu k^3$$

$C_1 = 1$  for correctly chosen units

There is a possible pre-factor, I put it = 1

and then  $[w \leftrightarrow -i \partial_t]$   
 $[k \leftrightarrow +i \partial_x]$

leads to  $-i \partial_t = i c_0 k x + i u k x - \nu k^3 x$   
 the  $c_0$  term can be re-absorbed by a re-definition of  $x$  (walk in the Moony frame, p18)

leading to =

$$[u_t + u u_x - \nu u_{xxx}] = 0$$

KdV = [conserved quantities and Lagrangian density = ]

for a general  $u(x,t)$  which goes to a constant when  $x \rightarrow \pm\infty$ .  
then, by a change of function ( $u \rightarrow u - u_0$ ) one can assume that this constant is zero [  $\int_{\mathbb{R}} v_t + \frac{v^2}{2} (u_0 + v) v_x + v_{xxx} = 0$  and the terms ].  
[  $v_0$  disappears if  $x \rightarrow \pm\infty - u_0$  ].

⇒ the quantity  $\left[ \int_{\mathbb{R}} u dx \right]$  is conserved since KdV reads

$$u_t + \left( \frac{u^2}{2} + u_{xx} \right)_x = 0$$

⇒ one also has  $\left[ \frac{(u^2)}{2}_t + \left[ \frac{u^3}{3} + uu_{xx} - \frac{1}{2}(u_x)^2 \right]_x \right] = 0$   
(momentum)  
(see below) indeed this reads  $uu_t + u^2 u_{xx} + uu_{xxx} - \cancel{u_x u_{xx}} - \cancel{u_x u_{xxx}} = 0$   
which agrees with KdV

hence  $\left[ \int_{\mathbb{R}} u^2 dx \right]$  is also conserved.

⇒ one has also  $\left[ (u^3 - 3u_x^2)_t + \left[ \frac{3}{4}u^4 + 3u^2 u_{xx} - 6u_x u_x^2 + 3u_{xx}^2 - 6u_x u_{xxx} \right]_x \right] = 0$   
energy density  
(see below)  $3u^2 u_t - 6u_x u_{xt} = -3u^2 u_x - 3u^2 u_{xxx}$   
 $u_t = -u_x u_x - u_{xxx} \Rightarrow$  (using KdV)  $+ 6u_x u_{xx} + 6u_x u_{(4x)}$   
 $u_{xt} = -u_x^2 - uu_{xx} - u_{(4x)}$

the divergence term reads:

$$\text{div} = 3u^2 u_x + 6u_x u_{xx} + 3u^2 u_{xxx} - 6u_x^3 - 12u_x u_{xxx} \\ + 6u_x u_{xxx} - 6u_x u_{xxx} - 6u_x u_{(4x)} =$$

This seems up to zero when added to the time-derivative term

These 2 last invariants are actually natural = they come from the Lagrangian character of KdV =

$$S = \int dx dt L \quad \text{where } L = \frac{1}{2}\varphi_t \varphi_t + \frac{1}{6}\varphi_x^3 - \frac{1}{2}(\varphi_{xx})^2$$

here it's unusual because  $L$  depends on  $\varphi_{xx}$ ! so, the

Euler-Lagrange eqs read:

$$\frac{\partial L}{\partial \varphi} = \partial_t \left( \frac{\partial L}{\partial \varphi_t} \right) + \partial_x \left( \frac{\partial L}{\partial \varphi_x} \right) - \partial_x^2 \left( \frac{\partial L}{\partial \varphi_{xx}} \right)$$

(unusual term)

in our system this gives:  $\mathcal{O} = \frac{1}{2}\varphi_{xt} + \left(\frac{1}{2}\varphi_{tt} + \frac{1}{2}\varphi_x^2\right)_x + \varphi_{xxxx} = 0$  (26)

$$\Leftrightarrow \mathcal{O} = \varphi_{xt} + \varphi_x \varphi_{xx} + \varphi_{xxxx} = 0 = \text{this is KdV}$$

for  $u = \varphi_x$

- the usual way of getting energy conservation is here slightly modified by the  $\varphi_{xx}$  contribution to  $\mathcal{L}$ : one writes

$$\partial_t \mathcal{L} = \frac{\partial \mathcal{L}}{\partial \varphi} \varphi_t + \frac{\partial \mathcal{L}}{\partial \varphi_t} \varphi_{tt} + \frac{\partial \mathcal{L}}{\partial \varphi_x} \varphi_{xt} + \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \varphi_{xxt}$$

$$\hookrightarrow \text{Euler-Lagrange} = \partial_t \left( \frac{\partial \mathcal{L}}{\partial \varphi_t} \right) + \partial_x \left( \frac{\partial \mathcal{L}}{\partial \varphi_x} \right) - \partial_x^2 \left( \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \right)$$

this writes (regrouping the terms) =

$$\partial_t \mathcal{L} = \partial_t \left[ \frac{\partial \mathcal{L}}{\partial \varphi_t} \varphi_t \right] + \partial_x \left[ \frac{\partial \mathcal{L}}{\partial \varphi_x} \varphi_t \right] + \partial_x \left[ -\partial_x \left( \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \right) \varphi_t \right] + \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \varphi_{xt}$$

unusual contribution

hence one has:

$$0 = \partial_t \left( \frac{\partial \mathcal{L}}{\partial \varphi_t} \varphi_t - \mathcal{L} \right) + \partial_x \left[ \frac{\partial \mathcal{L}}{\partial \varphi_x} \varphi_t - \partial_x \left( \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \right) \varphi_t + \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \varphi_{xt} \right]$$

usual form of the energy

$$\text{density} = \frac{1}{2} \varphi_x \varphi_t - \left( \frac{1}{2} \varphi_{xt} \varphi_t + \frac{1}{6} \varphi_x^3 - \frac{1}{2} (\varphi_{xx})^2 \right) = \boxed{-\frac{1}{6} u^3 + \frac{1}{2} u_x^2 = \text{energy density}}$$

and here the Poynting vector is =

$$S = \frac{\partial \mathcal{L}}{\partial \varphi_x} \varphi_t - \partial_x \left( \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \right) \varphi_t + \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \varphi_{xt} = \left( \frac{1}{2} \varphi_t + \frac{1}{2} \varphi_x^2 \right) \varphi_t - \partial_x (-\varphi_{xx}) \varphi_t - \varphi_{xx} \varphi_{xt}$$

$$= \left( \frac{1}{2} \varphi_t + \frac{1}{2} \varphi_x^2 + \varphi_{xxx} \right) \varphi_t - \varphi_{xx} \varphi_{xt},$$

$\varphi_t$  is no nice, but one notices that, from the

eqs of motion one has  $(\varphi_{xt})_x = -\partial_x \left( \frac{1}{2} \varphi_x^2 + \varphi_{xxx} \right) = -\left( \frac{u^2}{2} + u_{xx} \right)_x$

since this appears in a  $x$  derivative, I allow myself to replace  $\varphi_t$  by  $-\frac{u^2}{2} - u_{xx}$ . then one gets =

$$S = -\left( \frac{1}{4} u^2 + \frac{1}{2} u_{xx} \right) \left( \frac{1}{2} u^2 + u_{xx} \right) + u_x (u u_x + u_{xxx})$$

$$= -\frac{1}{8} u^4 - \frac{1}{2} u^2 u_{xx} - \frac{1}{2} (u_{xx})^2 + u u_x^2 + u_x u_{xxx}$$

and  $\boxed{E_t + S_x = 0}$  = same as the last eq. up to a factor (-6)  
 conservation  $\rightarrow$  green frame

→ momentum conservation:

$$\partial_x \mathcal{L} = \underbrace{\frac{\partial \mathcal{L}}{\partial \varphi_t} \varphi_x}_{\varphi_t} + \frac{\partial \mathcal{L}}{\partial \varphi_x} \varphi_{xt} + \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \varphi_{xx} + \frac{\partial \mathcal{L}}{\partial \varphi_{xxx}} \varphi_{xxx}$$

$$\hookrightarrow \partial_t \left( \frac{\partial \mathcal{L}}{\partial \varphi_t} \right) \varphi_x + \partial_x \left( \frac{\partial \mathcal{L}}{\partial \varphi_x} \right) \varphi_x - \partial_x^2 \left( \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \right) \varphi_x$$

hence

$$\partial_x \mathcal{L} = \partial_t \left( \frac{\partial \mathcal{L}}{\partial \varphi_t} \varphi_x \right) + \partial_x \left( \frac{\partial \mathcal{L}}{\partial \varphi_x} \varphi_x \right) + \partial_x \left[ -\partial_x \left( \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \right) \varphi_x + \frac{\partial \mathcal{L}}{\partial \varphi_{xxx}} \varphi_{xx} \right]$$

thus

$$\partial_t \left( \frac{\partial \mathcal{L}}{\partial \varphi_t} \varphi_x \right) + \partial_x \left( \frac{\partial \mathcal{L}}{\partial \varphi_x} \varphi_x \right) - \mathcal{L} - \partial_x \left( \frac{\partial \mathcal{L}}{\partial \varphi_{xx}} \right) \varphi_x + \frac{\partial \mathcal{L}}{\partial \varphi_{xxx}} \varphi_{xx} = 0$$

$$\text{momentum density} = \frac{1}{2} (\varphi_x)^2 = \frac{u^2}{2}$$

$$\begin{aligned} & \frac{1}{2} \varphi_t \varphi_{tt} + \frac{1}{2} \varphi_x^3 - \frac{1}{2} \varphi_u \varphi_{tt} - \frac{1}{6} \varphi_x^3 + \frac{1}{2} (\varphi_{xx})^2 \\ & + \varphi_{xxx} \varphi_x - (\varphi_{xx})^2 = \frac{u^3}{3} - \frac{1}{2} (u_x)^2 + u u_{xx} \end{aligned}$$

$$\text{on retrouve } \left( \frac{u^2}{2} \right)_t + \left( \frac{u^3}{3} + u u_{xx} - \frac{1}{2} u_x^2 \right)_x = 0 \text{ comme page 25.}$$

→ note culturelle. KdV a ceci de particulier qu'en + de ces 3 quantités conservées, elle en a une infinité d'autres, ~~mais~~  
en voici quelquesunes =  $\begin{cases} \frac{u^4}{4} - 3u u_x^2 + \frac{2}{5} u_{xx}^2 \\ \frac{u^5}{5} - 6u^2 u_x^2 + \frac{36}{5} u u_{xx}^2 - \frac{108}{35} u_{xxx}^2 \\ \dots \text{etc} \dots \end{cases}$

note on replace of  $\varphi_t$  by  $-\left(\frac{u^2}{2} + u_{xx}\right)$   
this replace<sup>t</sup> is allowed because when one computes  $\varphi_{xx}$ , there remain a term  $\varphi_t$ , but it is in factor of  $\varphi_{tt} + \frac{1}{2} (\varphi_x)^2 + \varphi_{4xx}$  which is zero.  
Then, all what remains is either  $\varphi_{tt}$  ( $= -\varphi_x \varphi_{xx} - \varphi_{4xx} = -u u_x - u_{xxx}$ ) or spatial derivations of  $\varphi$

\* Real space:

$\alpha \exp[-\tilde{R}(x-Vt)]$

Since in this region the soliton is a small perturbation of the background, one can perform a linear expansion similar to what is done for  $\exp[ikx - i\omega t]$

$$\text{with } \begin{cases} \tilde{R} = -ik \\ \tilde{k}V = -i\omega \end{cases}$$

since the dispersion relation is  $\omega = f(k)$  one will have:

$$\frac{\tilde{k}V}{-i} = f(k) \left( \frac{\tilde{R}}{-i} = ik \right) \quad \text{where } f(k) = \omega k - k^3$$

This yields  $\tilde{k}V = -i(\omega ik - (ik)^3) = \omega \tilde{k} + \tilde{k}^3$   
 hence  $V = \omega_0 + \tilde{k}^2$  since, of course  $\tilde{k} \sim 1/L$  (of the plot)

One gets  $V \sim \omega_0 + 1/L^2$

↙ better derivation than  
on page 23