

# Rice method for the extremes of Gaussian fields

Saclay, June 15 2011

**Jean-Marc Azaïs**

Institut de Mathématiques, Université de Toulouse

## Examples

The record method  $d = 2$  or  $3$

The maxima method  
Second order

Processes defined on fractal sets

# Signal + noise model

Spatial Statistics often uses “signal + noise model”, for example :

- ▶ precision agriculture
- ▶ neuro-sciences
- ▶ sea-waves modelling

# Signal + noise model

Spatial Statistics often uses “signal + noise model”, for example :

- ▶ precision agriculture
- ▶ **neuro-sciences**
- ▶ sea-waves modelling

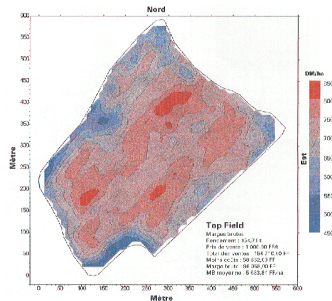
# Signal + noise model

Spatial Statistics often uses “signal + noise model”, for example :

- ▶ precision agriculture
- ▶ neuro-sciences
- ▶ sea-waves modelling

# Precision agriculture

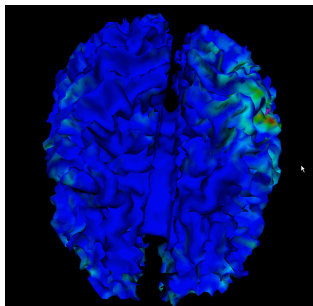
Representation of the yield per unit by GPS harvester .



Is there only noise or some region with higher fertility ??

# Neuroscience

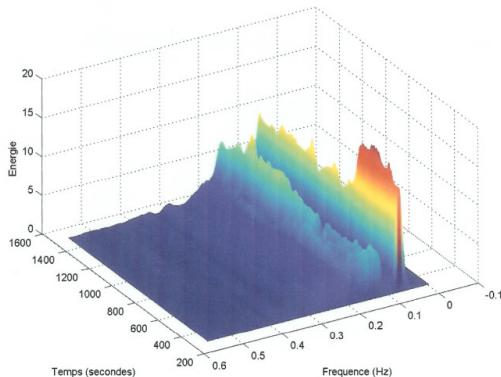
The activity of the brain is recorded under some particular action and the same question is asked



source : Maureen CLERC

# Sea-waves spectrum

Locally in time and frequency the spectrum of waves is registered.  
We want to localize transition periods.





In all these situations a good statistics consists in observing the **maximum** of the (absolute value) of the random field for deciding if it is **typically** (Noise) or **too large** (signal).

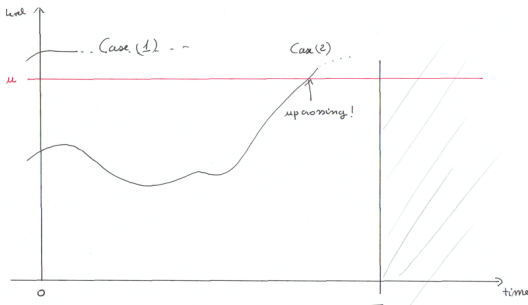
# The Rice method

$M$  is the maximum of a smooth random process  $X(t)$ ,  $t \in \mathbb{R}^d$  ( $d = 1$ ) or field ( $d > 1$ ).

We want to evaluate

$$\mathbb{P}\{M > u\}$$

In dimension 1 : count the number of up-crossing



# The Rice formula

If  $X(t)$  is a regular (differentiable) process  $\mathbb{R} \rightarrow \mathbb{R}$  or a random field  $\mathbb{R}^d \rightarrow \mathbb{R}^d$  and if we consider its number of zeros :

$$N_u = \#\{t \in [0, T] : X(t) = u\} (d = 1)$$

We obtain a random variable. In general nothing is known except for the moments of this variable.

For the **expectation**, for random processes ( $d = 1$ ) we get the simplest version of the Rice formula :

$$\mathbb{E}(N_u) = \int_0^T \mathbb{E}(|X'(t)| | X(t) = u) p_{X(t)}(u),$$

where  $p$  is the density

The proof of this formula is based on some generalization of the change of variable formula. It explains the term  $|X'(t)|$  .

For  $X : \mathbb{R}^d \rightarrow \mathbb{R}^d$ ,  $d > 1$  we must put  $|\det(X'(t))|$ .

In larger dimension search for an other geometrical characteristic

- ▶ number of connected component of the excursion set : open problem
- ▶ Euler characteristic an alternative to the preceding : Conceptually complicated, computationally easy no bounds
- ▶ Number of maxima above the considered level : difficult to compute the determinant but gives bounds
- ▶ Particular points on the level set : the record method

In larger dimension search for an other geometrical characteristic

- ▶ number of connected component of the excursion set : **open problem**
- ▶ **Euler characteristic an alternative to the preceding :**  
**Conceptually complicated, computationally easy no bounds**
- ▶ Number of maxima above the considered level : **difficult to compute the determinant but gives bounds**
- ▶ Particular points on the level set : the record method

In larger dimension search for an other geometrical characteristic

- ▶ number of connected component of the excursion set : **open problem**
- ▶ Euler characteristic an alternative to the preceding : **Conceptually complicated, computationally easy no bounds**
- ▶ **Number of maxima above the considered level : difficult to compute the determinant but gives bounds**
- ▶ Particular points on the level set : the record method

In larger dimension search for an other geometrical characteristic

- ▶ number of connected component of the excursion set : open problem
- ▶ Euler characteristic an alternative to the preceding : Conceptually complicated, computationally easy no bounds
- ▶ Number of maxima above the considered level : difficult to compute the determinant but gives bounds
- ▶ Particular points on the level set : the record method



# The maxima method

Let us forget the boundary

$\{M > u\} =$  There is a maximum above  $u =: \{M_u > 0\}$

$$\begin{aligned} \mathbb{P}\{M > u\} &\leq \mathbb{E}(M_u) \\ &= \int_u^{+\infty} dx \int_S \mathbb{E} [|\det(X''(t))| \mathbf{1}_{X''(t) < 0} \mid X(t) = x, X'(t) = 0] P_{X(t), X'(t)}(x, 0) dt \end{aligned}$$

Very difficult to compute : the expectation of absolute value of the determinant

## Examples

The record method  $d = 2$  or  $3$

The maxima method  
Second order

Processes defined on fractal sets

Under some conditions, Roughly speaking the event

$$\{M > u\}$$

is almost equal to the events

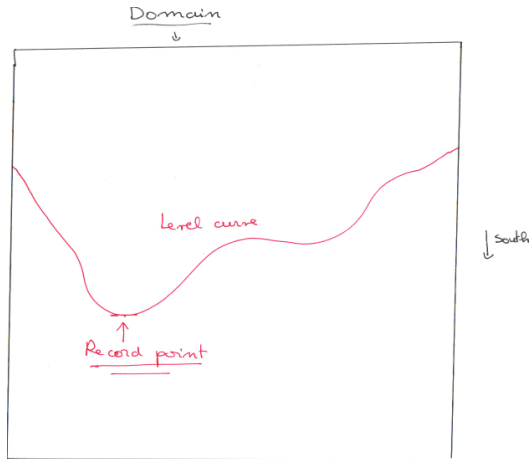
"The level curve at level  $u$  is non-empty"

"The point at the southern extremity of the level curve exists"

"There exists a point on the level curve :

$$X(t) = u; X'_1(t) = \frac{\partial X}{\partial t_1} = 0; X'_2(t) = \frac{\partial X}{\partial t_2} > 0$$

$$X''_{11}(t) = \frac{\partial^2 X}{\partial t_1^2} < 0"$$



# Forget the boundary

and define

$$Z(t) := \begin{pmatrix} X(t) \\ X'_1(t) \end{pmatrix}$$

The probability above is bounded by the expectation of the number of roots of  $Z(t) - (u, 0) \Rightarrow$  Rice formula

$$\mathbb{P}\{M > u\} \leq \text{Boundary terms}$$

$$+ \int_S \mathbb{E}(|\det(Z'(t)) \mathbf{1}_{X''_1(t) < 0} \mathbf{1}_{X'_2(t) > 0}| | X(t) = u, X'_1(t) = 0) p_{X(t), X'_1(t)}(u, 0) dt,$$

The difficulty lies in the **computation of the expectation of the determinant**

The trick is that under the condition  $\{X(t) = u, X'_1(t)\} = 0$ , the quantity

$$|\det(Z'(t))| = \begin{vmatrix} X'_1 & X'_2 \\ X''_{11} & X''_{12} \end{vmatrix}$$

is simply **equal to  $|X'_2 X''_{11}|$** . Taking into account conditions, we get the following expression for the second integral

$$\int_S E(|X''_{11}(t) - X'_2(t)^+ | X(t) = u, X'_1(t) = 0) p_{X(t), X'_1(t)}(u, 0) dt.$$

Moreover under stationarity or some more general hypotheses, these two **random variables are independent**.

## Theorem

*Suppose that the set  $S$  is the square  $[0, T]^2$  and that the process is stationary isotrope with  $E(X(t)) = 0$ ,  $\text{var}(X(t)) = 1$ ,  $\text{var}(X'(t)) = Id$  and satisfies some regularity conditions.*

*Then*

$$\mathbb{P}\{M > u\} \leq \bar{\Phi}(u) + \sqrt{2/\pi} T \phi(u) + T^2/(2\pi) [c\phi(u/c) + u\Phi(u/c)]\phi(u)$$

## Extension to dimension 3

Using Fourier method (Li and Wei 2009) we are able to compute the expectation of the absolute value of a determinant in dimension 2.

**It is a simple quadratic form.**

We are able to extend the result to dimension 3 (Pham 2010).

$$\begin{aligned} \mathbb{P}\{M > u\} \leq & 1 - \Phi(u) + \frac{2\sigma_1(S)}{\sqrt{2\pi}}\varphi(u) + \frac{\sigma_2(S)\varphi(u)}{4\pi} \left[ \sqrt{12\rho'' - 1} \varphi\left(\frac{u}{\sqrt{12\rho'' - 1}}\right) + \right. \\ & \left. + \frac{\sigma_3(S)\varphi(u)}{(2\pi)^{\frac{3}{2}}} \left[ u^2 - 1 + \frac{(8\rho'')^{\frac{3}{2}} \exp(-u^2 \cdot (24\rho'' - 2)^{-1})}{\sqrt{24\rho'' - 2}} \right] \right], \end{aligned}$$

$\sigma_1$  caliper diameter ;  $\sigma_2$  perimeter,  $\sigma_3$  Lebesgue measure.



## Examples

The record method  $d = 2$  or  $3$

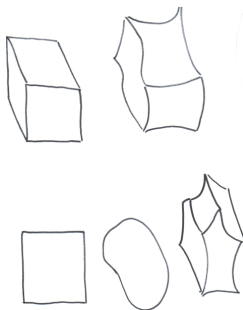
The maxima method  
Second order

Processes defined on fractal sets

Consider a realization with  $M > u$ , then necessarily there exist a local maxima or a border maxima above  $U$

Border maxima : local maxima in relative topology

If the consider sets that are union of manifolds of dimension 1 to  $d$  of this kind



In fact result are simpler (and stronger) in term of the density  $p_M(x)$  of the maximum. Bound for the distribution are obtained by integration.

## Theorem

$$p_M(x) \leq \hat{p}_M(x) := \frac{1}{2} [\bar{p}_M(x) + p_M^{EC}(x)] \text{ with}$$

$$\bar{p}_M(x) := \int_S \mathbb{E}(|\det(X''(t))|/X(t) = x, X'(t) = 0) p_{X(t), X'_j(t)}(x, 0) dt + \text{boundary term}$$

and

$$p_M^{EC}(x) := (-1)^d \int_S \mathbb{E}(\det(X''(t))/X(t) = x, X'(t) = 0) p_{X(t), X'_j(t)}(x, 0) dt + \text{boundary term}$$

Quantity  $p_M^{EC}(x)$  is easy to compute using the work by Adler and properties of symmetry of the order 4 tensor of variance of  $X''$  ( under the conditional distribution )

## Lemma

$$E(\det(X''(t))/X(t) = x, X'(t) = 0) = \det(\Lambda)H_d(x)$$

where  $H_d(x)$  is the  $d$ th Hermite polynomial and  $\Lambda := \text{Var}(X'(t))$

main advantage of Euler characteristic method lies in this result.

# computation of $\bar{p}_m$

The key point is the following

If  $X$  is stationary and isotropic with covariance  $\rho(\|t\|^2)$  normalized by  $\text{Var}(X(t)) = 1$  et  $\text{Var}(X'(t)) = Id$

Then under the condition  $X(t) = x, X'(t) = 0$

$$X''(t) = \sqrt{8\rho''} G + \xi \sqrt{\rho'' - \rho'^2} Id + x Id$$

Where  $G$  is a **GOE matrix (Gaussian Orthogonal Ensemble)**, and  $\xi$  a standard normal independent variable. We use recent result on the the characteristic polynomials of the GOE. Fyodorov(2004)

## Theorem

Assume that the random field  $\mathcal{X}$  is centered, Gaussian, stationary and isotropic and is “regular” Let  $S$  have polyhedral shape. Then,

$$\bar{p}(x) = \varphi(x) \left\{ \sum_{t \in S_0} \hat{\sigma}_0(t) + \sum_{j=1}^{d_0} \left[ \left( \frac{|\rho'|}{\pi} \right)^{j/2} H_j(x) + R_j(x) \right] g_j \right\} \quad (1)$$

- ▶  $g_j = \int_{S_j} \hat{\theta}_j(t) \sigma_j(dt)$ ,  $\hat{\sigma}_j(t)$  is the normalized solid angle of the cone of the extended outward directions at  $t$  in the normal space with the convention  $\sigma_d(t) = 1$ .  
For convex or other usual polyhedra  $\hat{\sigma}_j(t)$  is constant on faces of  $S_j$ ,
- ▶  $H_j$  is the  $j$  th (probabilistic) Hermite polynomial.

## Theorem (continued)

$$\blacktriangleright R_j(x) = \left( \frac{2\rho''}{\pi|\rho'|} \right)^{\frac{j}{2}} \frac{\Gamma((j+1)/2)}{\pi} \int_{-\infty}^{+\infty} T_j(v) \exp\left(-\frac{v^2}{2}\right) dy$$

$$v := -(2)^{-1/2}((1 - \gamma^2)^{1/2}y - \gamma x) \quad \text{with} \quad \gamma := |\rho'|(\rho'')^{-1/2}, \quad (2)$$

$$T_j(v) := \left[ \sum_{k=0}^{j-1} \frac{H_k^2(v)}{2^k k!} \right] e^{-v^2/2} - \frac{H_j(v)}{2^j(j-1)!} I_{j-1}(v), \quad (3)$$

$$I_n(v) = 2e^{-v^2/2} \sum_{k=0}^{\lfloor \frac{n-1}{2} \rfloor} 2^k \frac{(n-1)!!}{(n-1-2k)!!} H_{n-1-2k}(v) \quad (4)$$

$$+ \mathbf{1}_{\{n \text{ even}\}} 2^{\frac{n}{2}} (n-1)!! \sqrt{2\pi} (1 - \Phi(x))$$

# Second order study

Using an exact implicit formula

## Theorem

*Under conditions above +  $\text{Var}(X(t)) \equiv 1$  Then*

$$\lim_{x \rightarrow +\infty} -\frac{2}{x^2} \log [\hat{p}_M(x) - p_M(x)] \geq 1 + \inf_{t \in S} \frac{1}{\sigma_t^2 + \bar{\lambda}(t) \kappa_t^2}$$

$$\sigma_t^2 := \sup_{s \in S \setminus \{t\}} \frac{\text{Var}(X(s) | X(t), X'(t))}{(1 - r(s, t))^2}$$

*and  $\kappa_t$  is some geometrical characteristic et  $\Lambda_t = \text{GEV}(\Lambda(t))$*

The right hand side is finite and  $> 1$



## Examples

The record method  $d = 2$  or  $3$

The maxima method  
Second order

Processes defined on fractal sets

In some applications we consider a Gaussian stationary process defined on a **fractal set**. For example the level set of some fractal function.

It is direct consequence of the results above that if  $X(t)$  is normalized (centred, var =1) and with differentiable paths :

$$\mathbb{P}\{M > u\} \simeq u^{d-1} \phi(u)$$

for a parameter set  $S$  with integer dimension  $d$ .

**What happens if the dimension  $d$  is fractal ? ? ?**

The answer is positive if the set is **Minkowsky measurable**.  
Let  $S^\epsilon$  is the tube of size  $\epsilon$  around  $S$ , we ask that

$$\lambda(S^\epsilon) \simeq C\epsilon^{n-d}.$$

$\lambda$  is the Lebesgue measure,  $n$  the dimension of the ambient space,  $C$  is called the Minkowski content.

The proof is based on the fact that for a large level  $u$  and except with a negligible probability, in a neighborhood of the set  $S$

- ▶ there is only one connected component above  $u$ .
- ▶ There is only one local maxima above  $u$
- ▶ The connected component is almost a ball with center the maxima (and random radius  $r$ )
- ▶ Roughly speaking, the maximum on  $S$  is large than  $u$  if the maximum belongs to  $S^r$ .

# Some references

**Adler** R.J. and **Taylor** J. E. *Random fields and geometry*. Springer.

**Azaïs**, J-M. and **Wschebor** M. *Level set and extrema of random processes and fields*, Wiley (2009).

**Mercadier**, C. (2006), Numerical Bounds for the Distribution of the Maximum of Some One- and Two-Parameter Gaussian Processes, *Adv. in Appl. Probab.* **38**, pp. 149–170.

**Pham V. H.**, C. (2009), The upper bound for the tail of the distribution of some Gaussian fields. *in preparation*

# THANK-YOU